



POTSDAM INSTITUTE FOR
CLIMATE IMPACT RESEARCH

Proximity based city growth

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Berlin, H 0110

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Motivation

B.J.L. Berry & A. Okulicz-Kozaryn 2011:

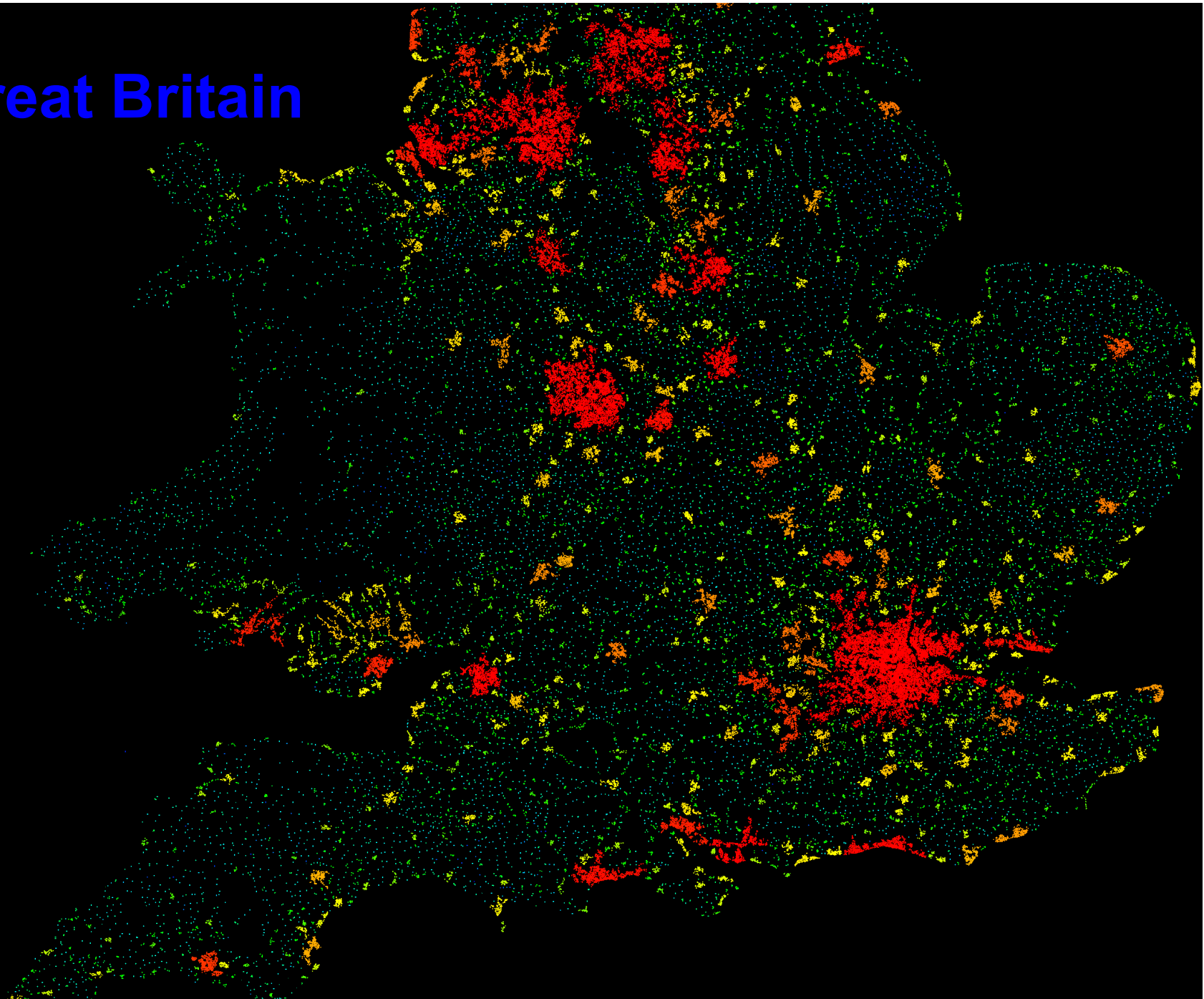
- identify different epochs of research on city size distributions
 - + An interesting empirical regularity (1913-1936)
 - + Zipf's Law (1939-...)
 - + Building a body of theory
 - + A stochastic steady-state
 - + Contemporary contentions
- raise three questions:
 1. What are the appropriate units of observation?
 2. Do the growth rates obey Gibrat's law?
 3. Does Zipf's Law apply in the upper tail?

1.+2. Rozenfeld et al., PNAS, 2008

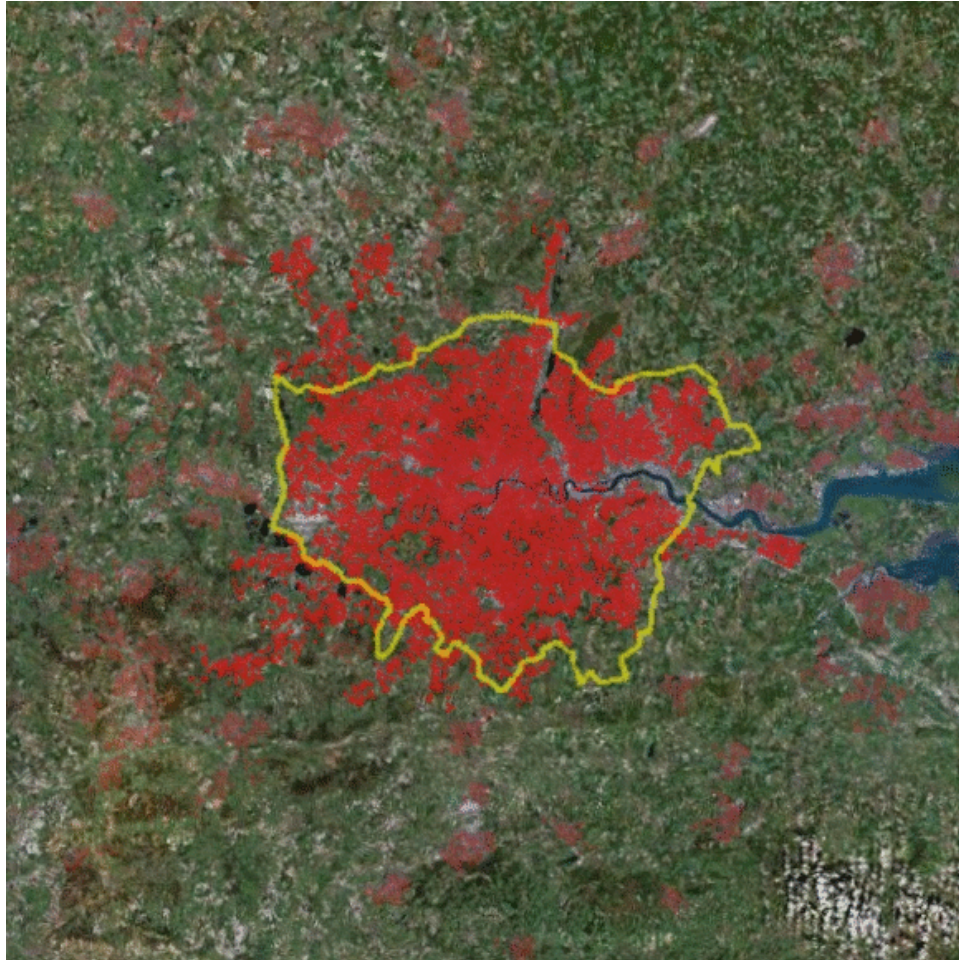
1.+3. Rozenfeld et al., AER, 2011

City Clustering Algorithm (CCA)

Great Britain



Greater London



First Law of Geography

*“Everything is related to everything else,
but near things are more related
than distant things.”*

(W.R. Tobler 1970)

Gravitation Concepts

G.A.P. Carrothers (1956): “An Historical Review of the Gravity and Potential Concepts of Human Interaction”

W.J. Reilly's law (1931): breaking point of boundary of equal attraction

D.L. Huff's law (1963/64): shopper attraction

P. Pöyhönen (1963): “A Tentative Model for the Volume of Trade between Countries”

[F. Simini (2012): “A universal model for mobility and migration patterns”]

... we reexamine the gravitation concept

Approach

The cells of a grid with the coordinates i can either be occupied ($w_i = 1$) or empty ($w_i = 0$). Iteratively each site is tested for being populated. Therefore, the probability to become populated is given by

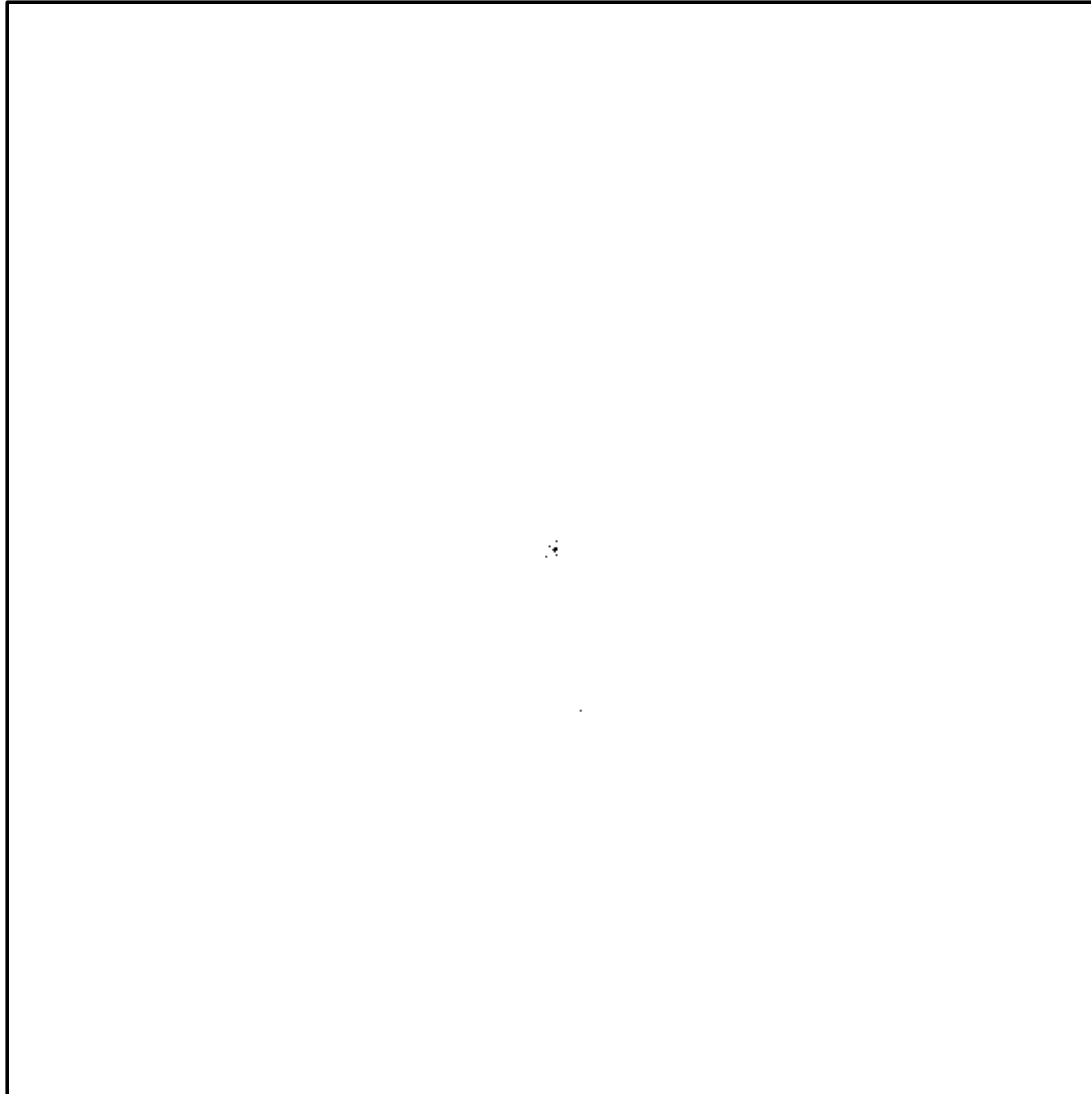
$$p_i = C \frac{\sum_{j \neq i} w_j d_{i,j}^{-\gamma}}{\sum_{j \neq i} d_{i,j}^{-\gamma}} , \quad (1)$$

where $d_{i,j}$ is the distance between the points i and j . The index j runs over all sites with $w_j = 0$, i.e. already populated sites are not further considered. Finally, the probabilities are normalized according to $\max(p_i) = 1$.

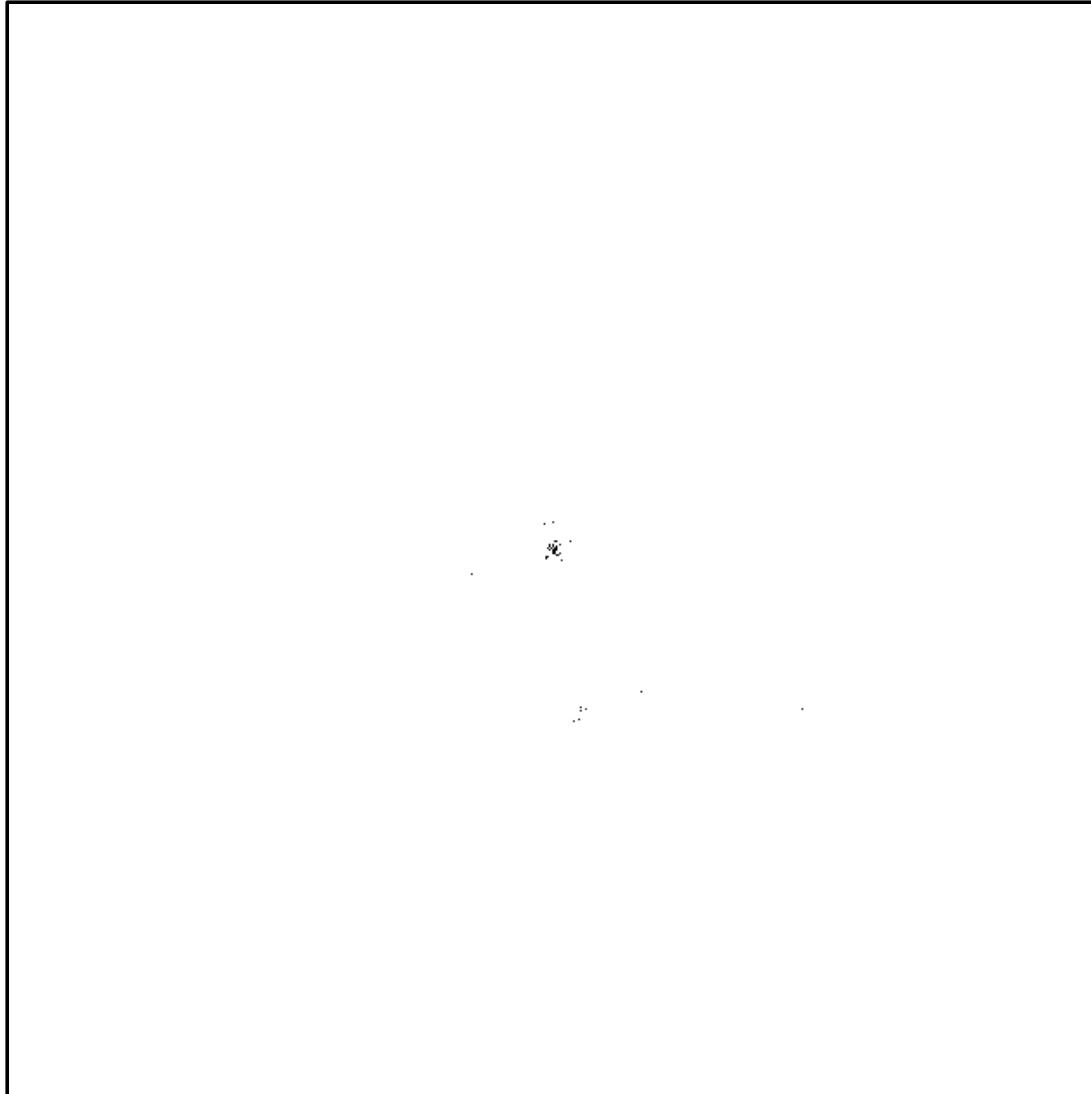
Example

630 x 630

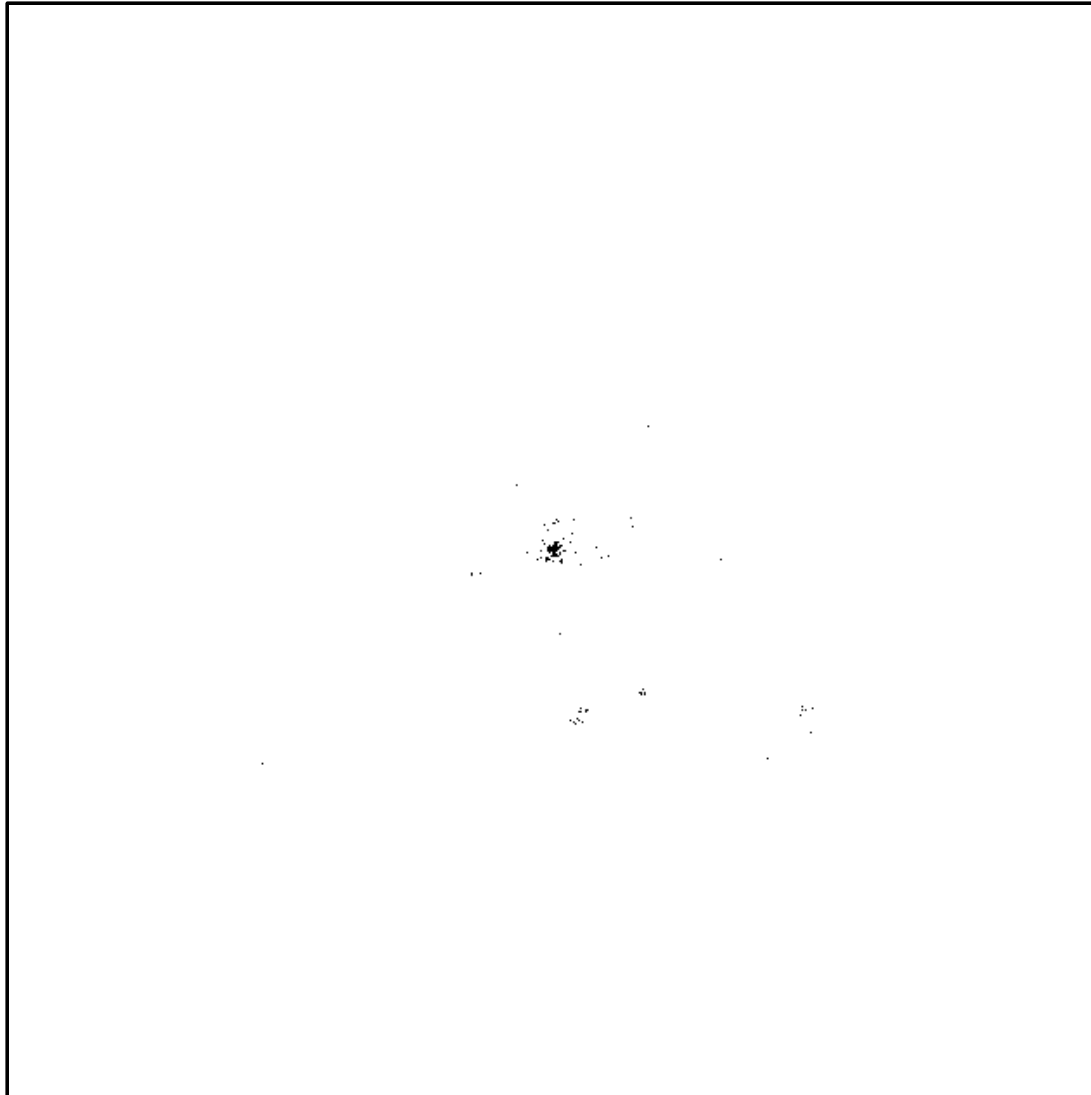
$\gamma=2.5$



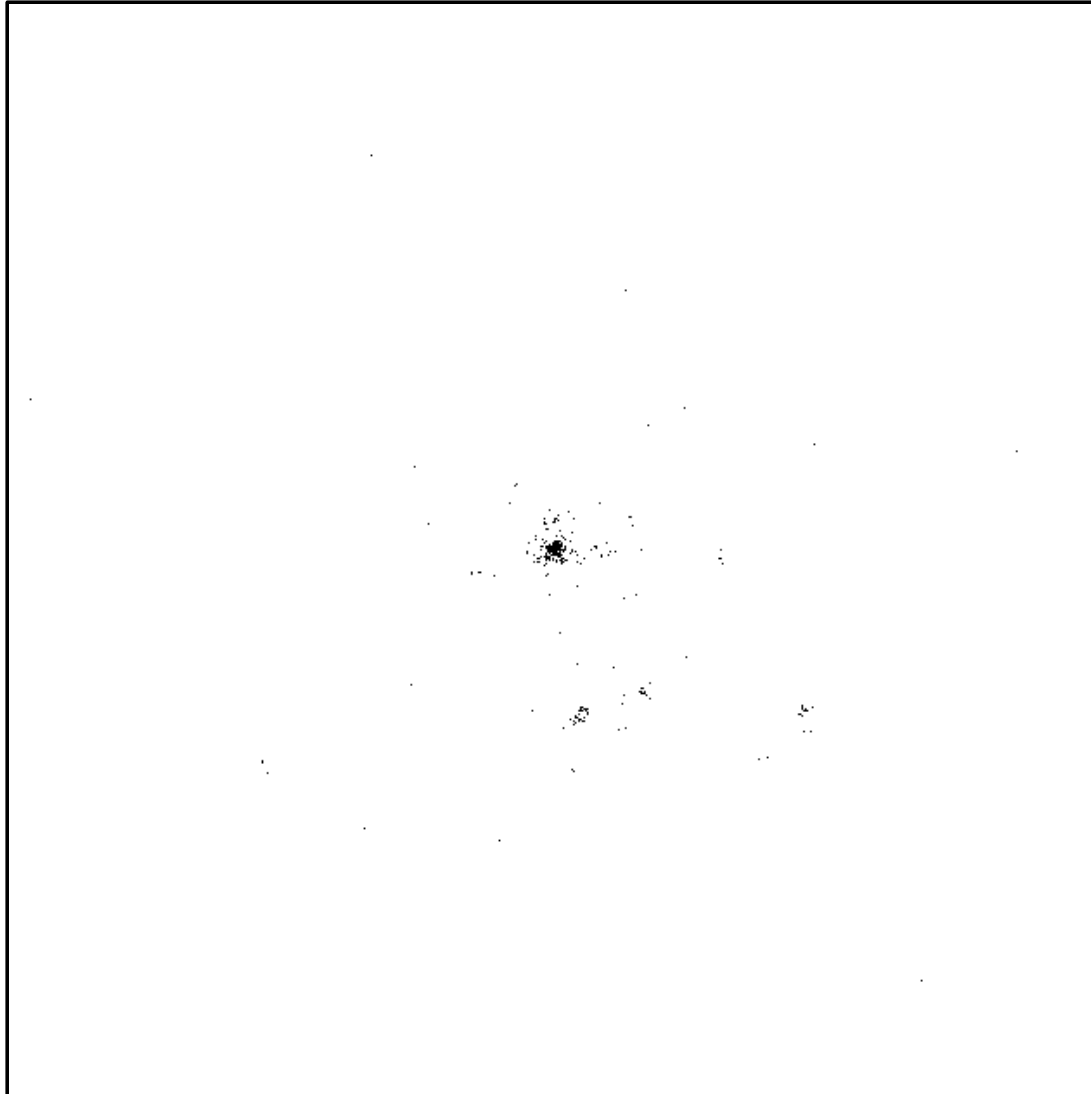
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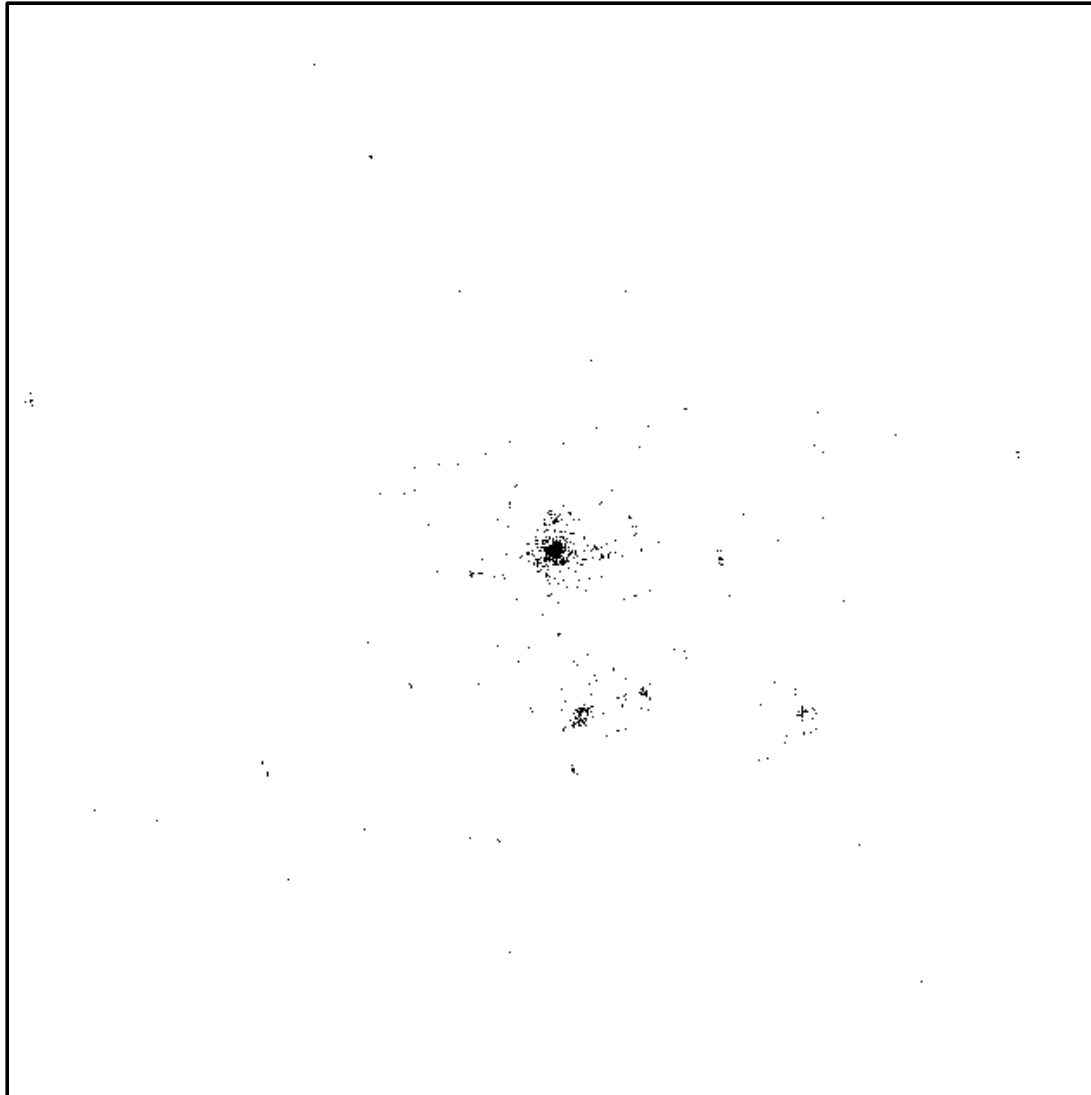
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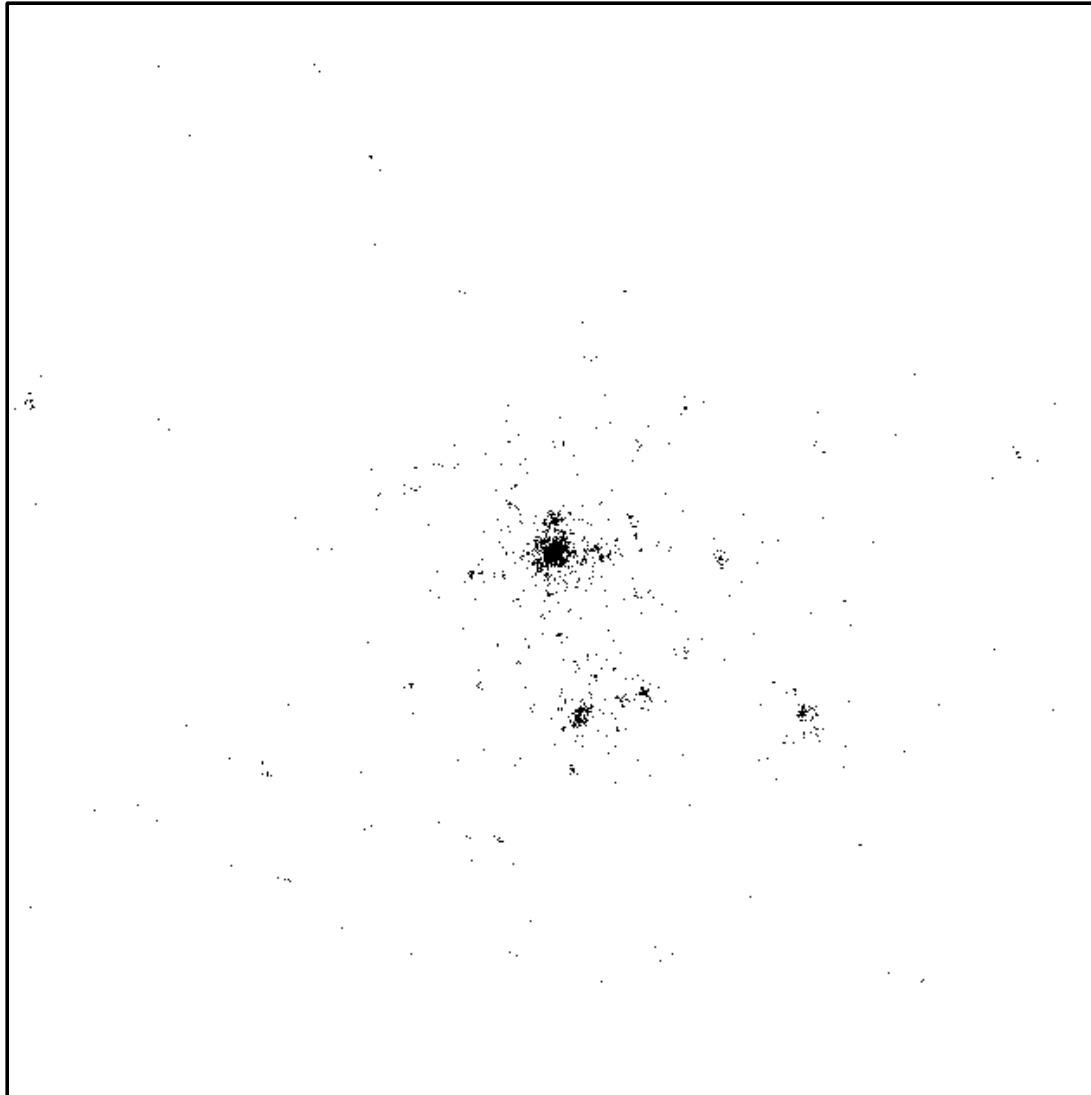
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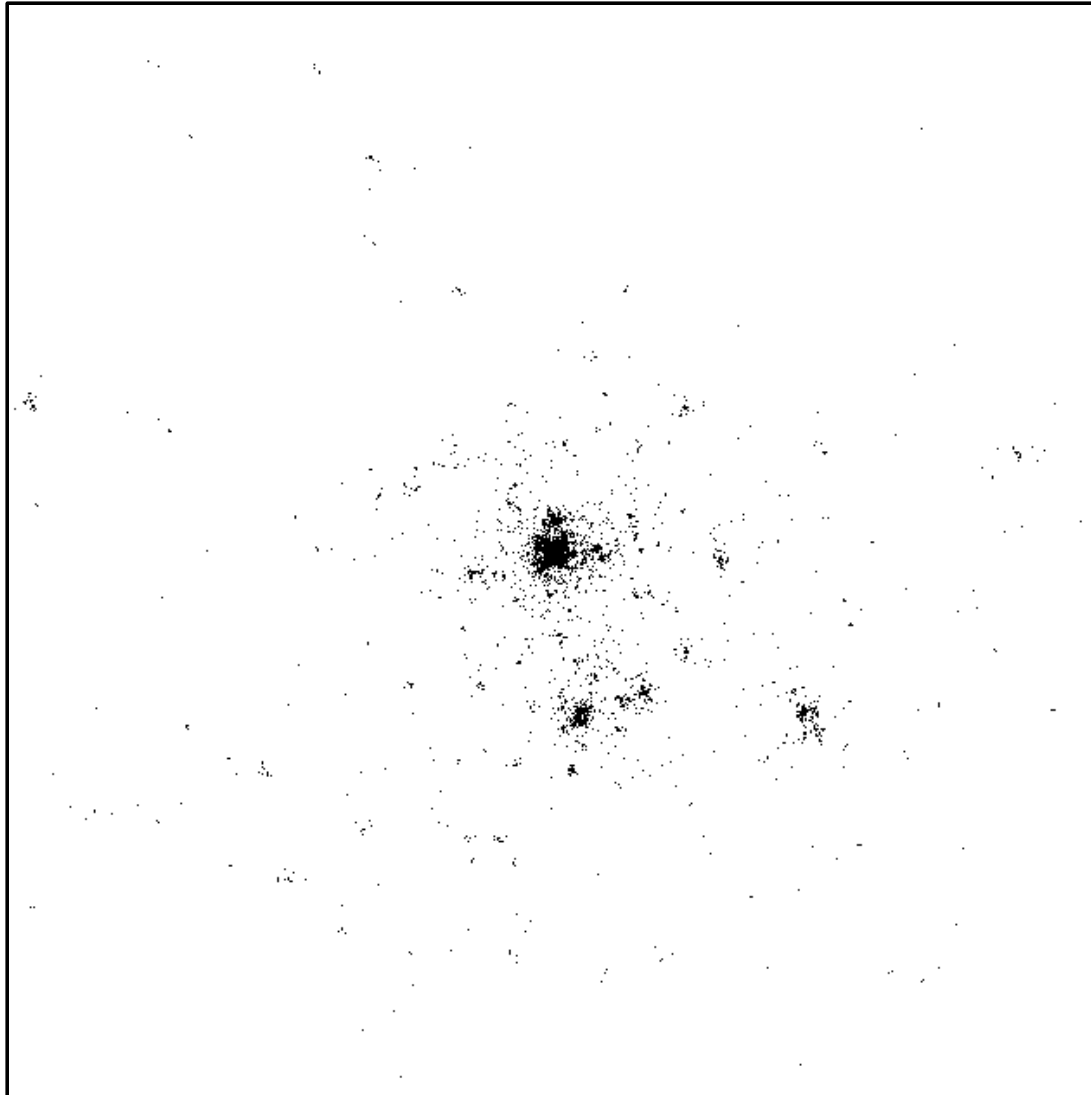
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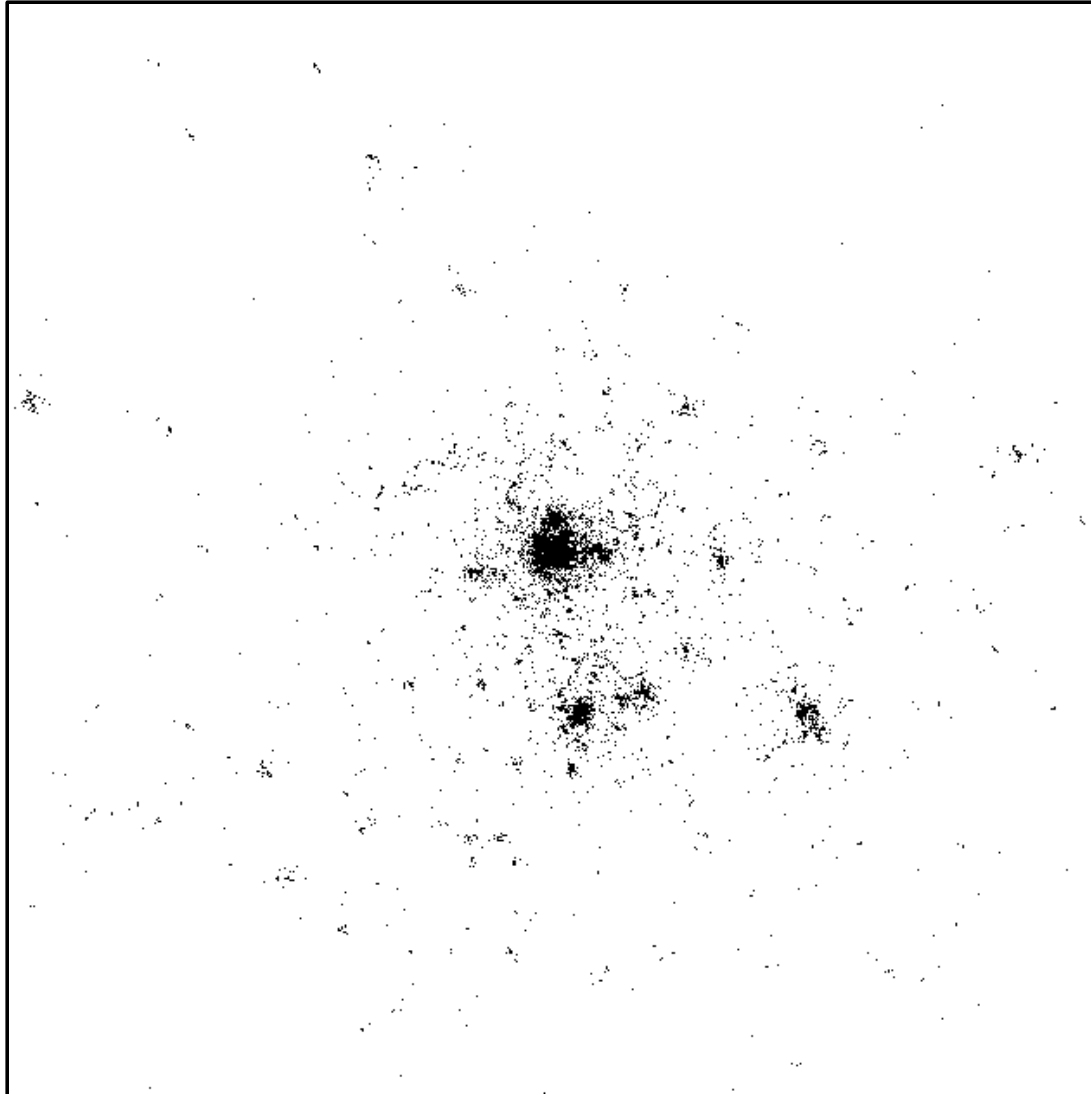
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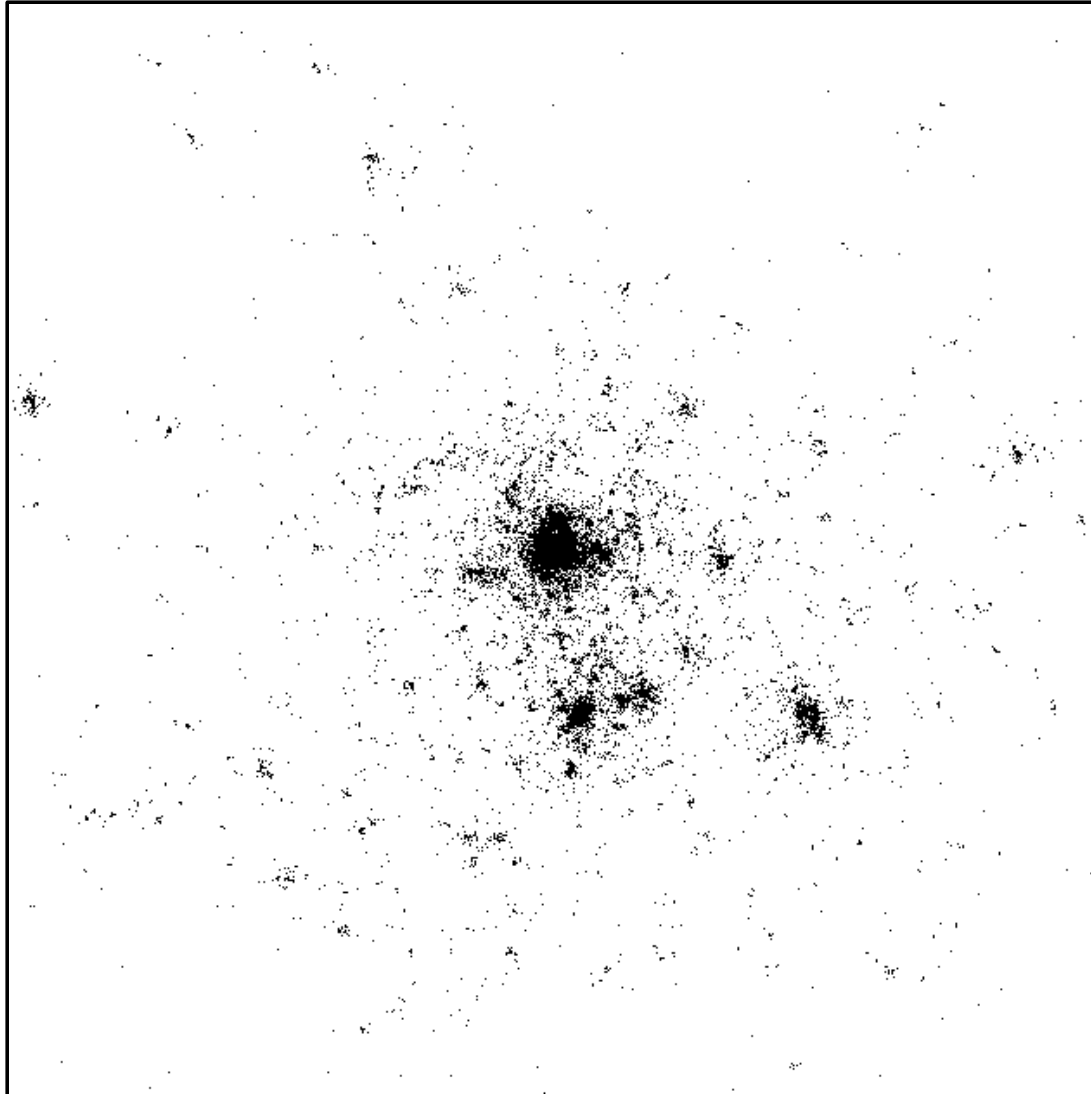
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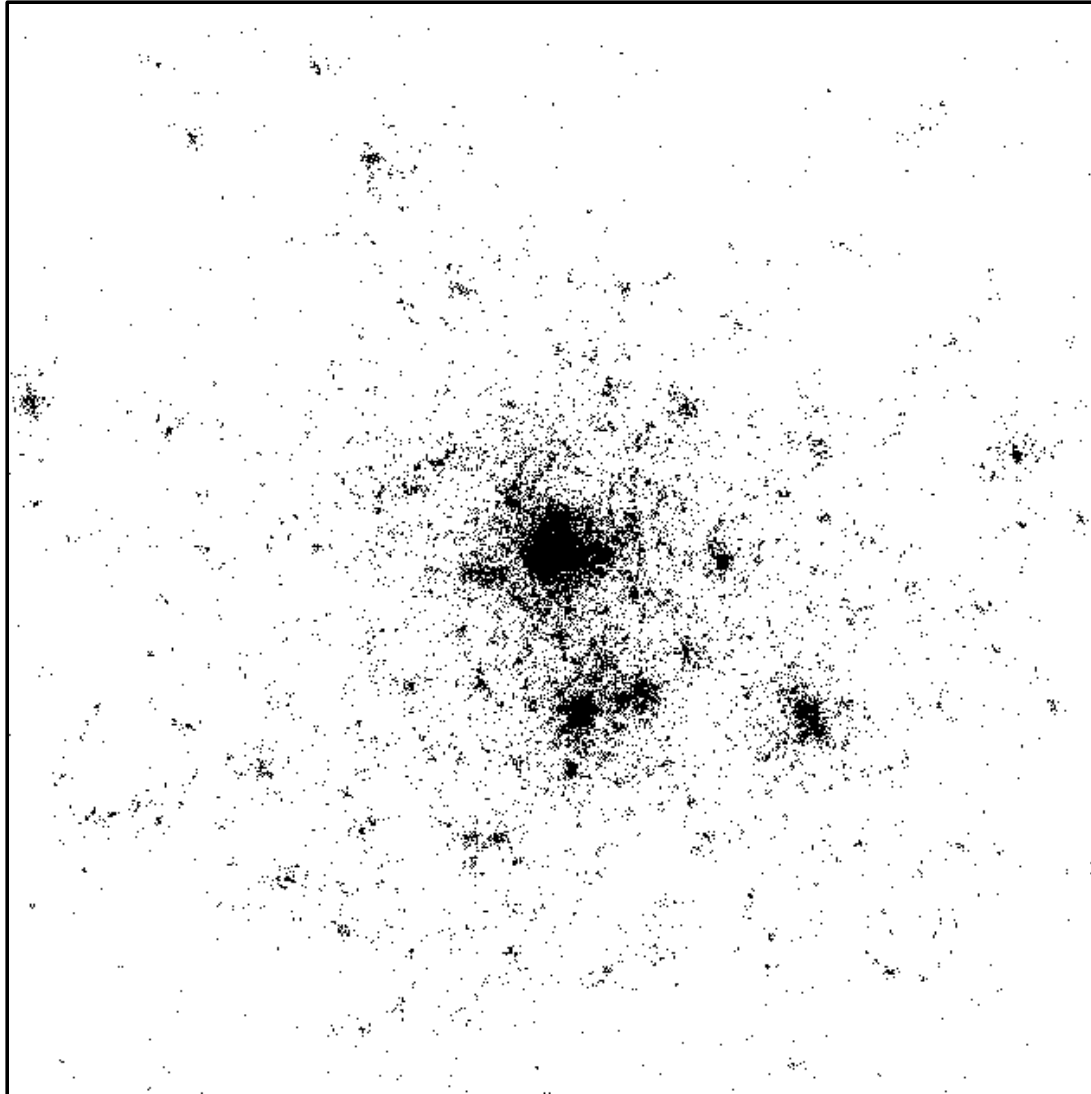
Example



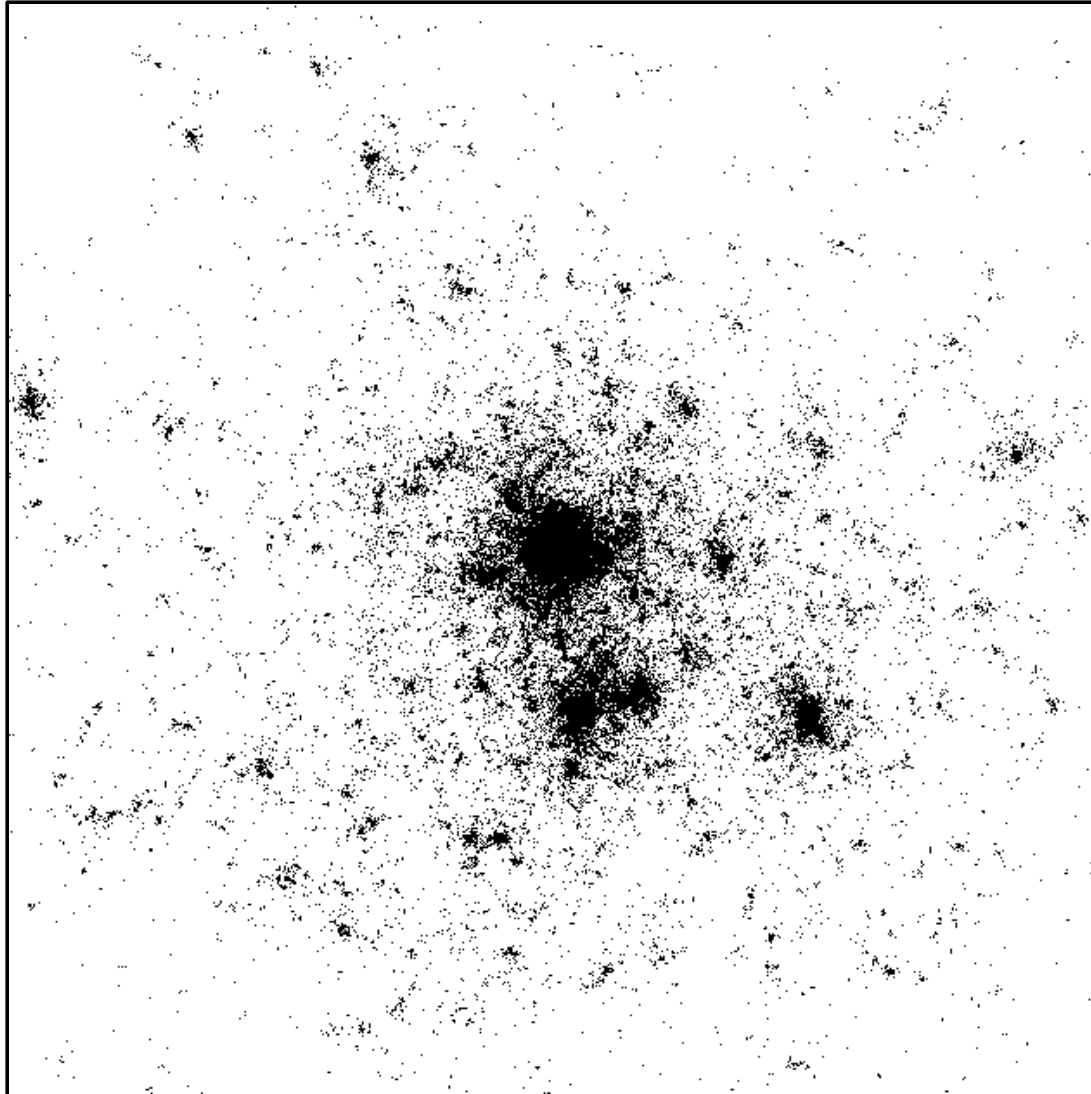
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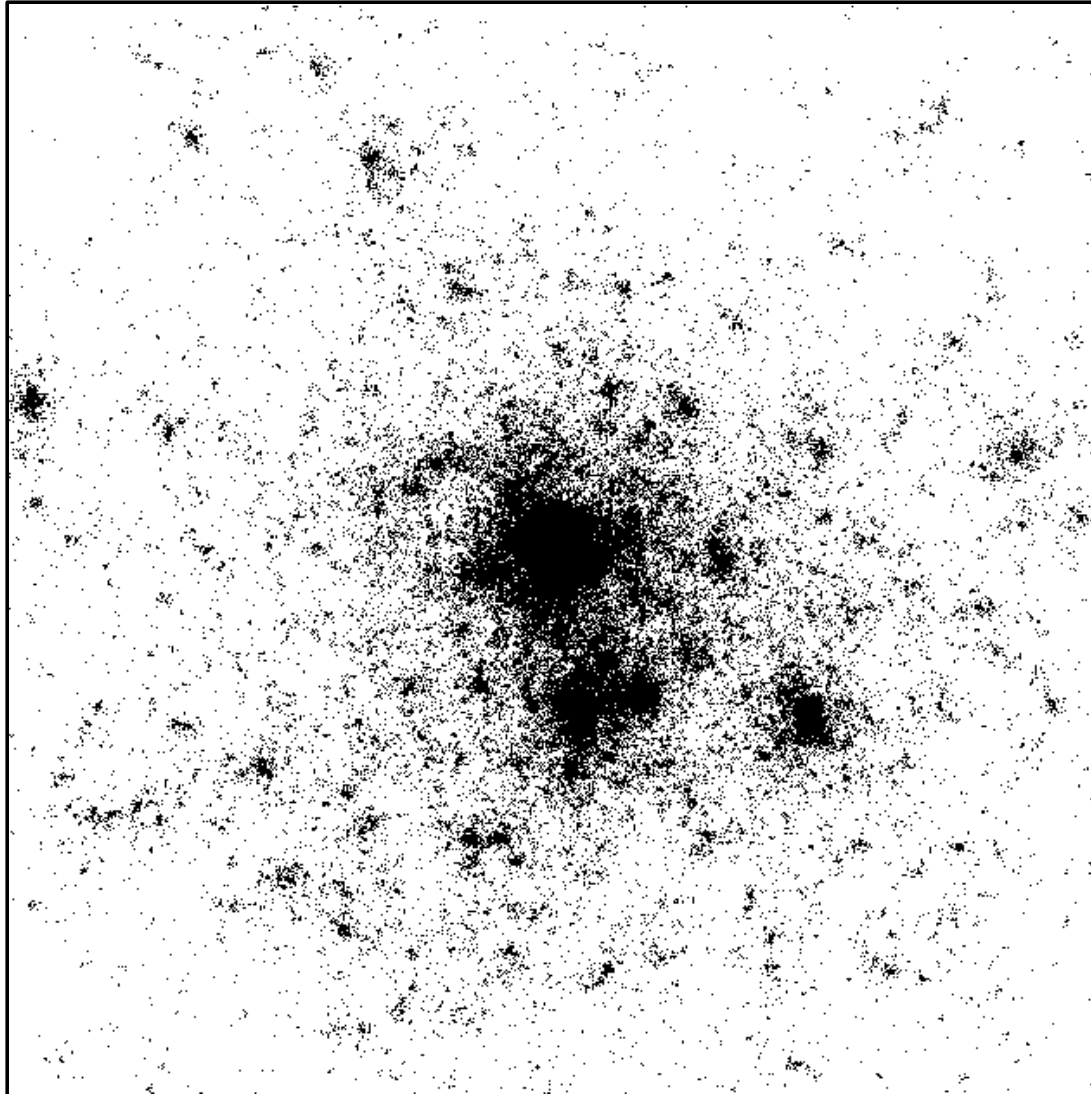
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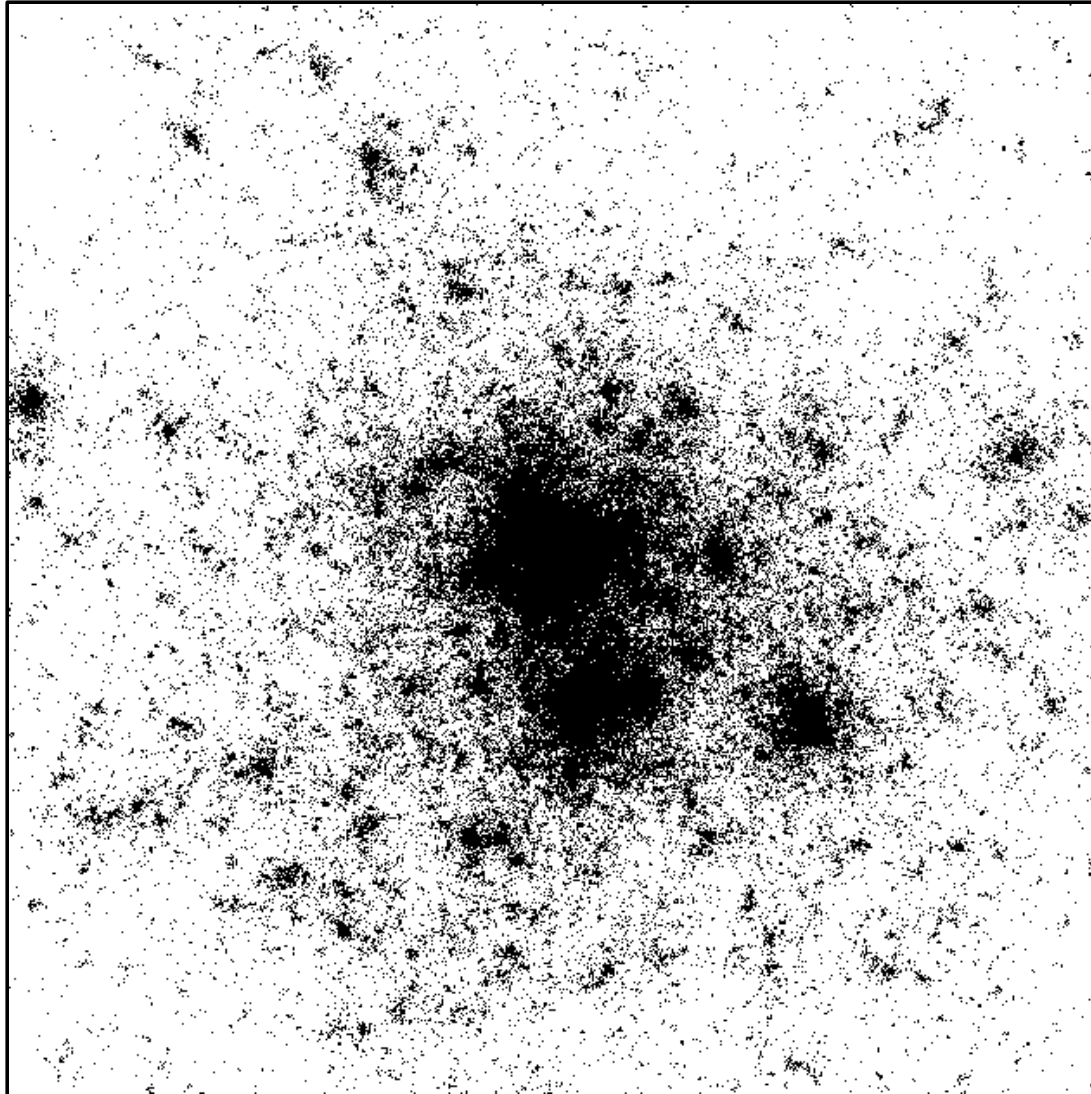
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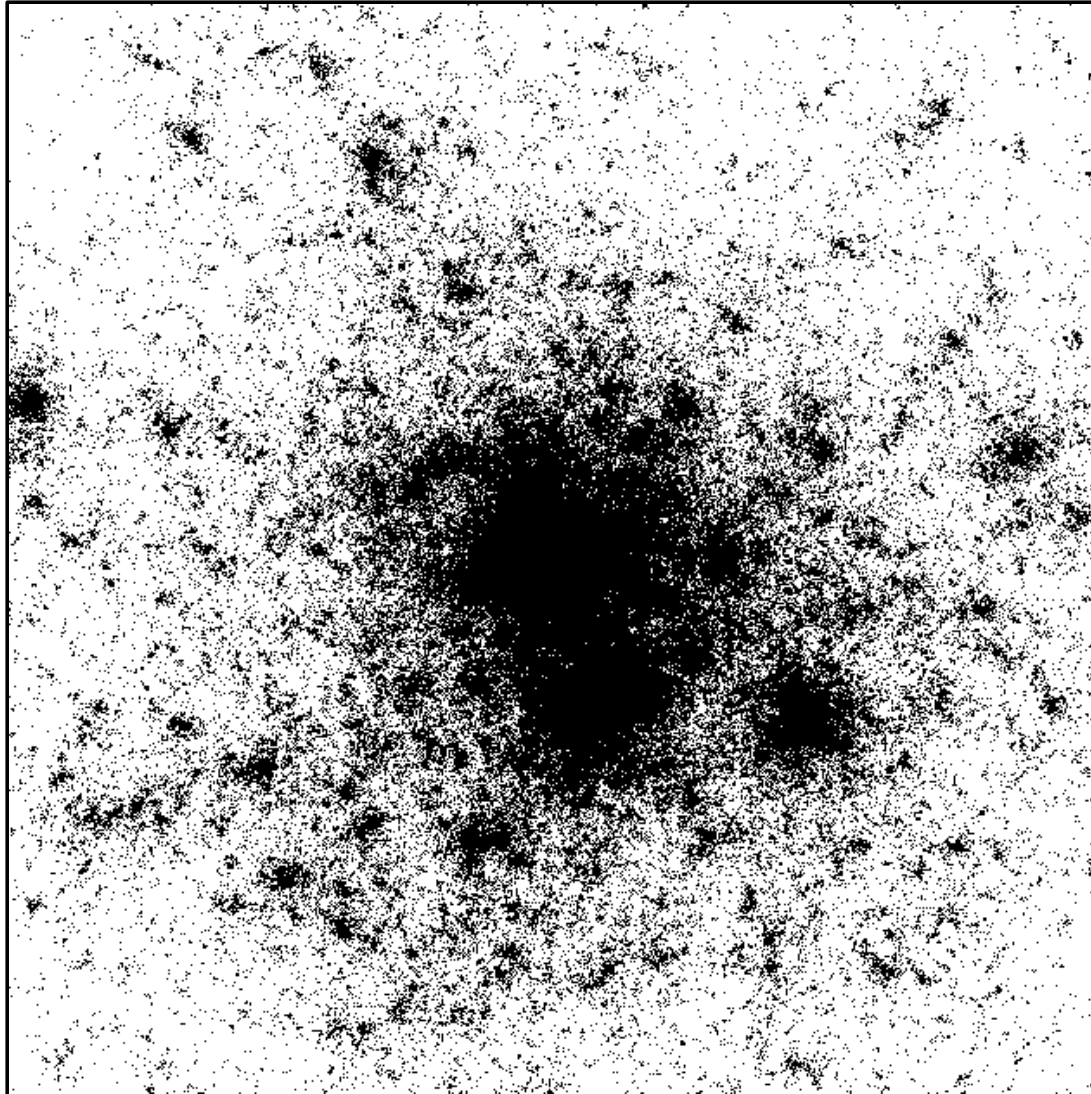
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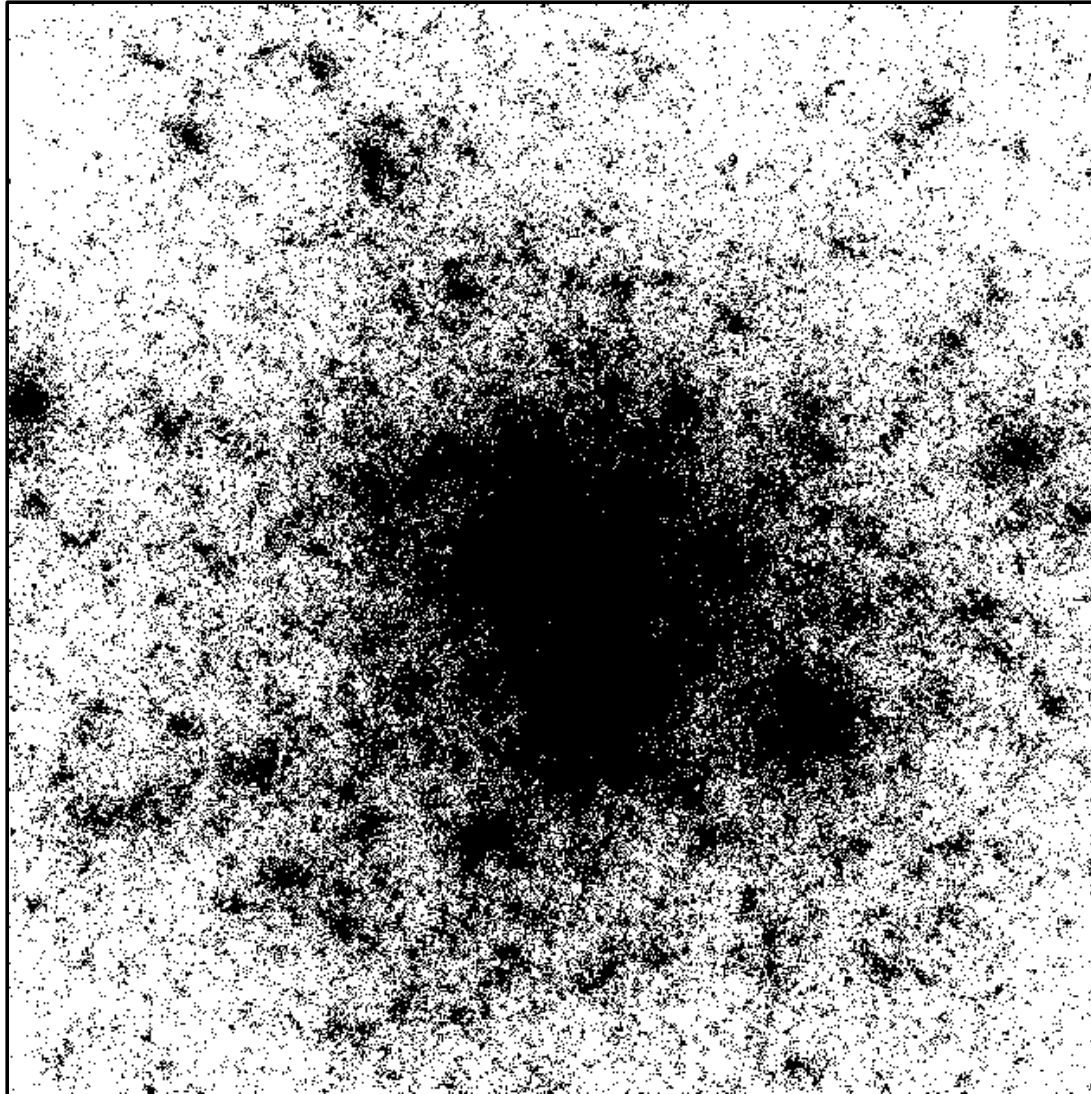
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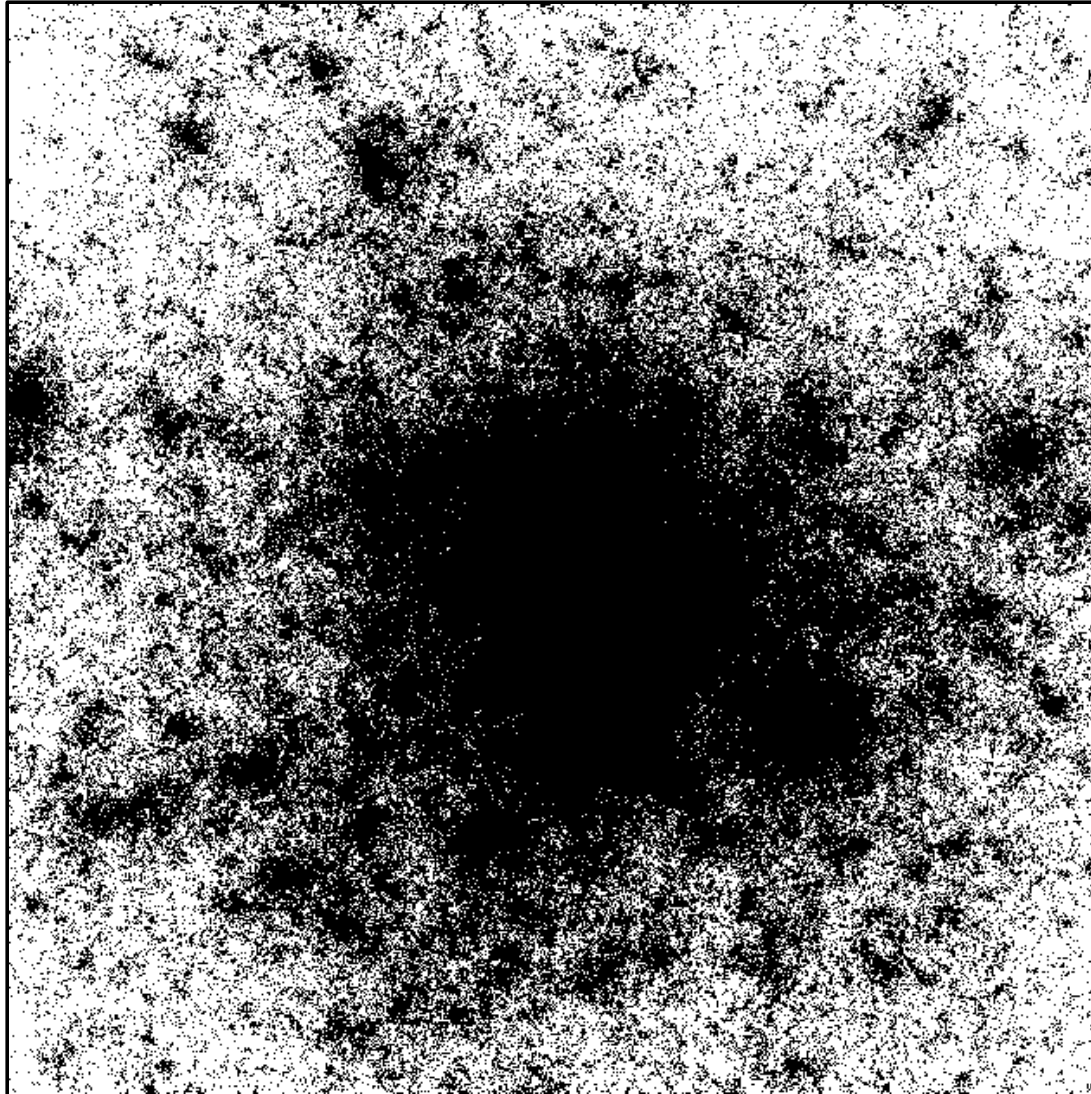
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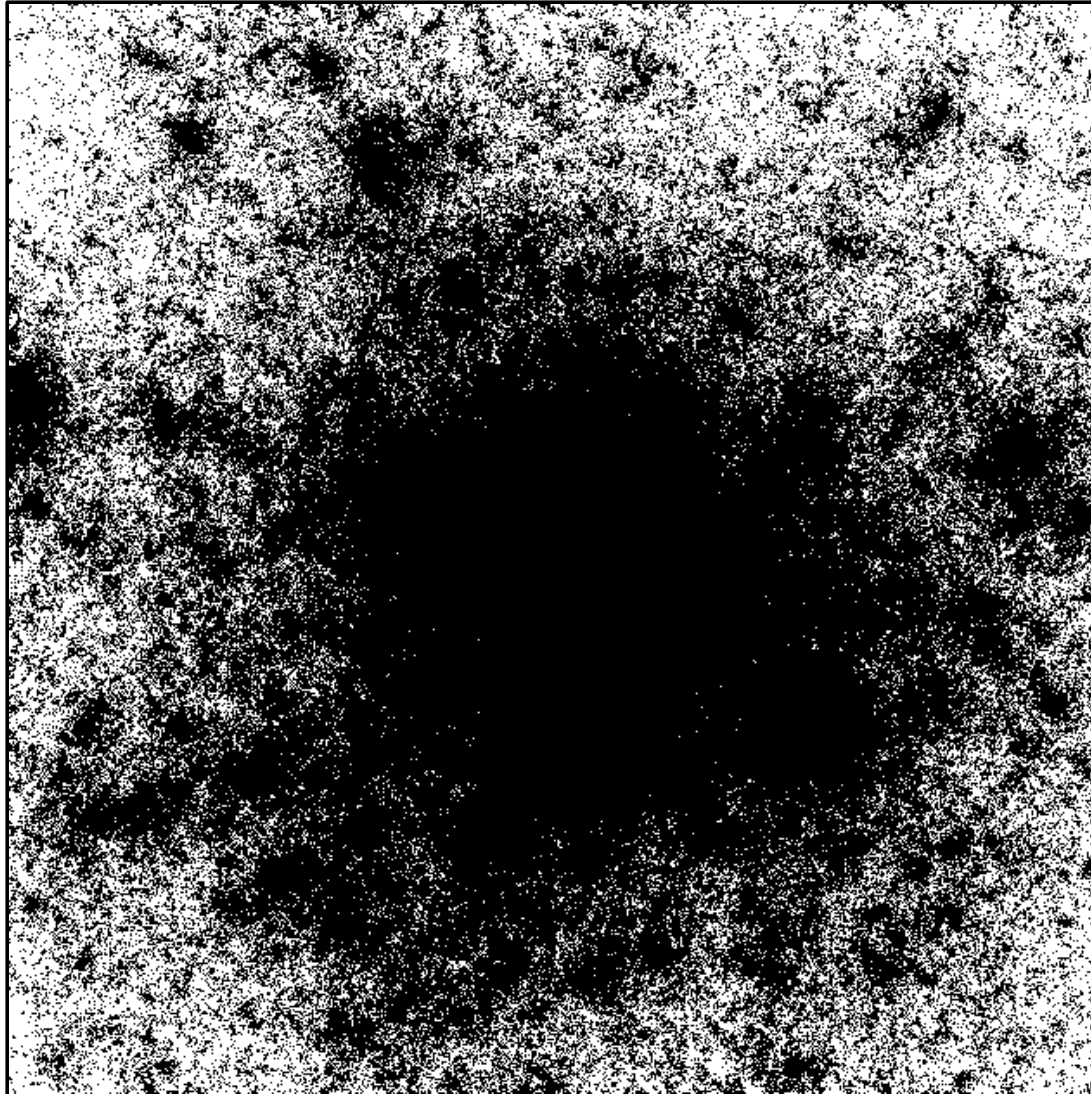
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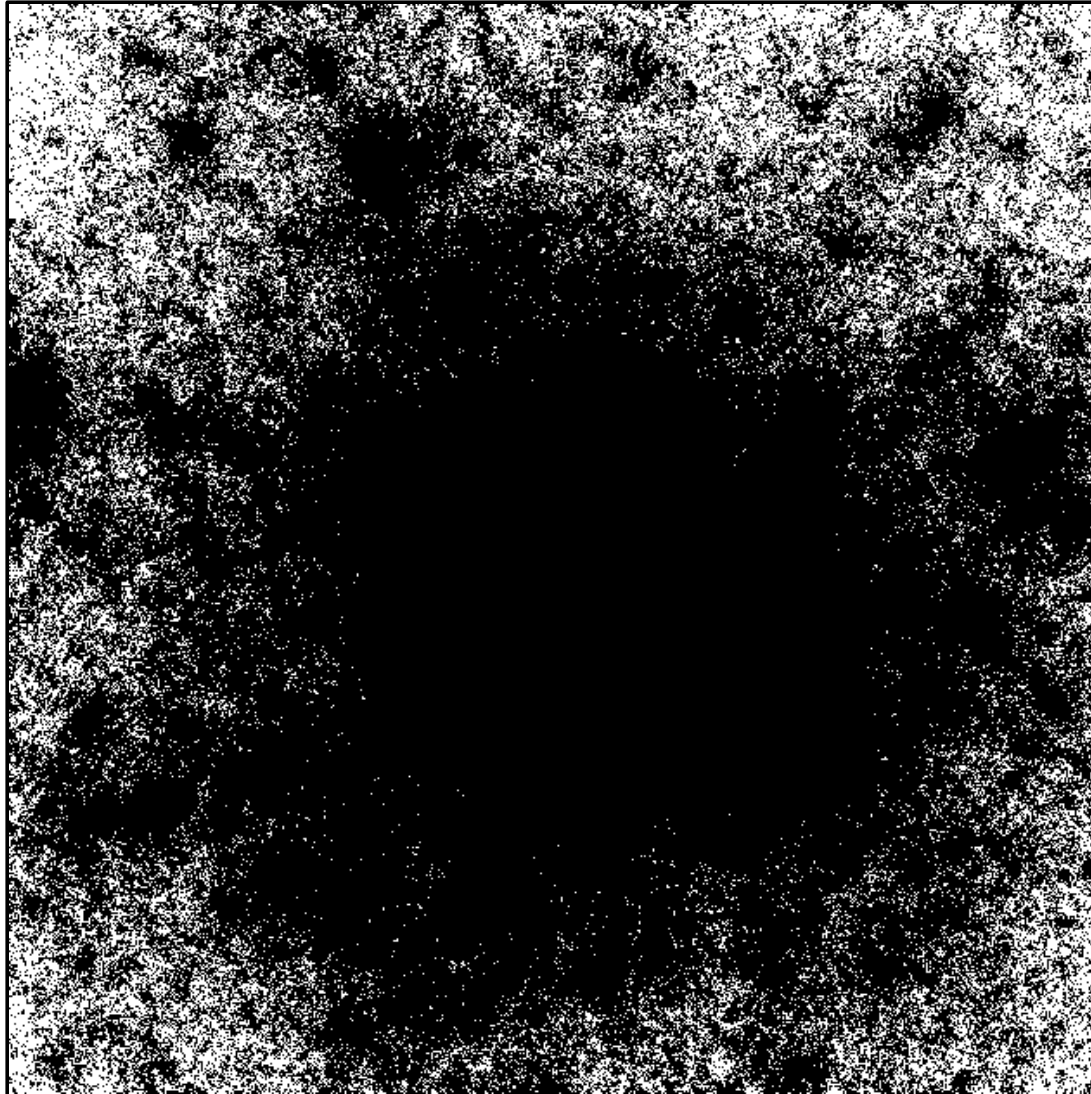
Example



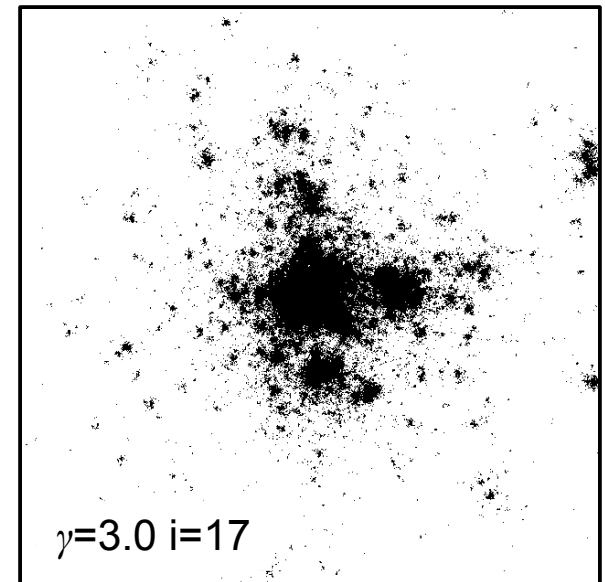
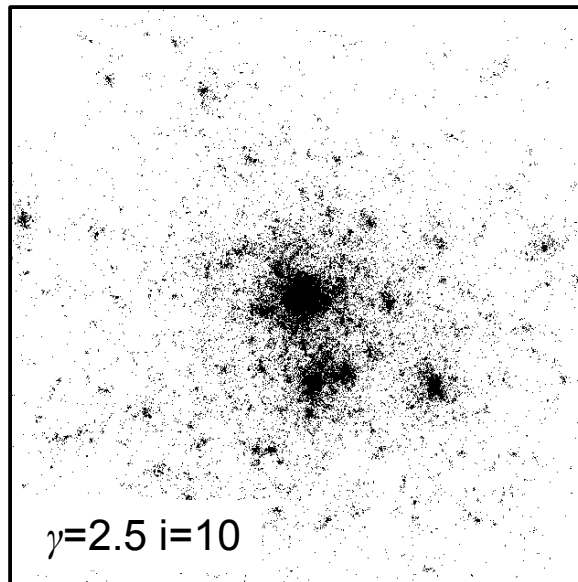
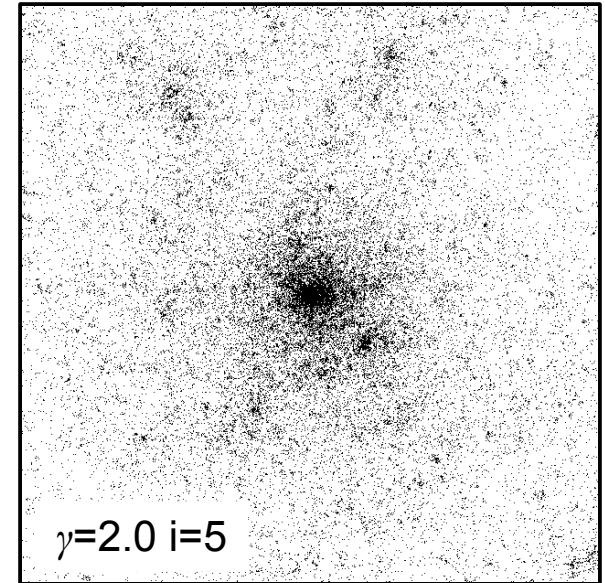
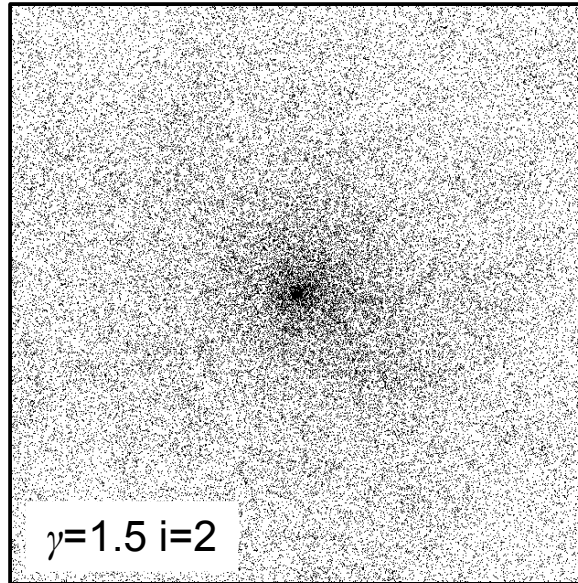
Example



Example ... end



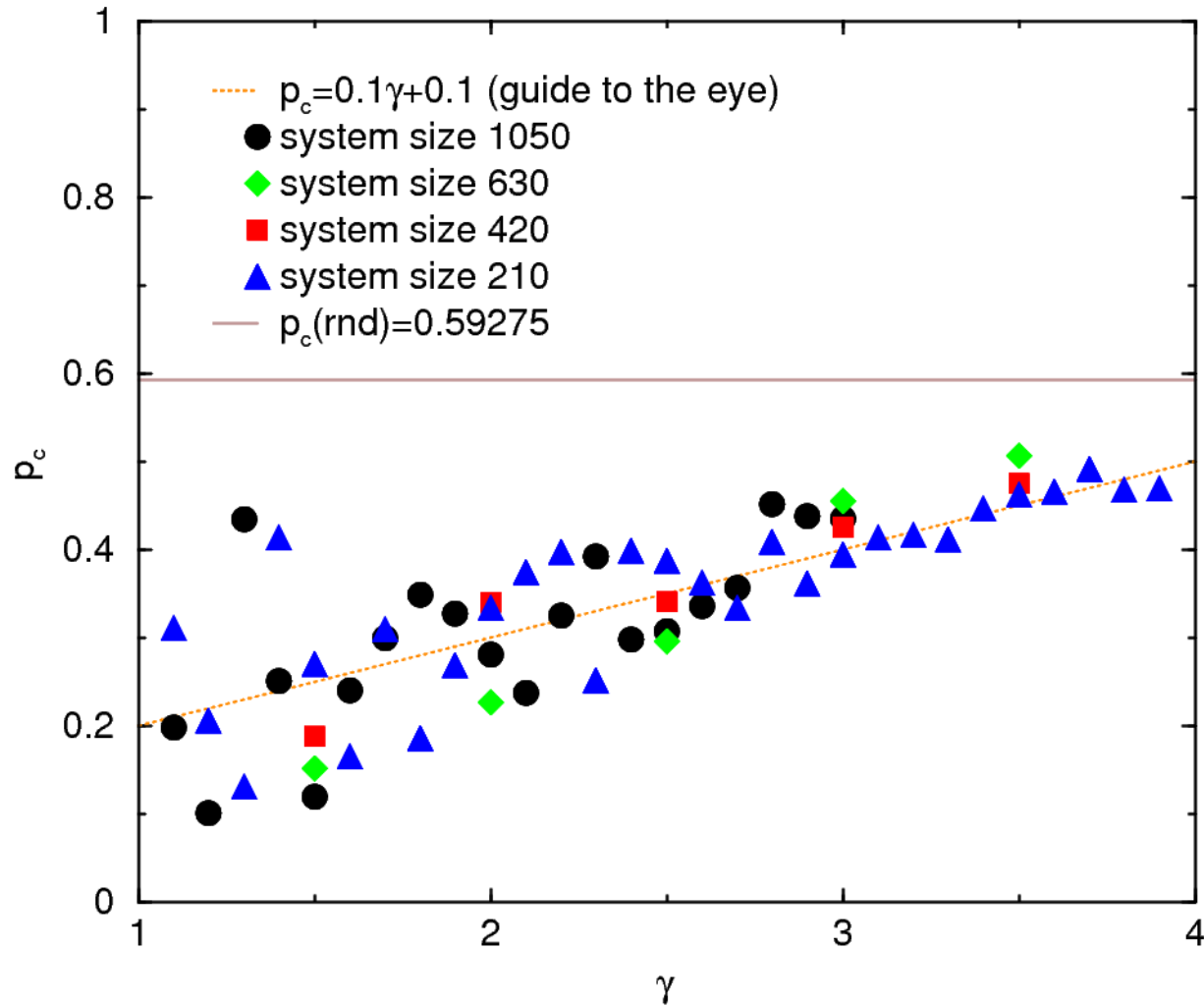
Exponent



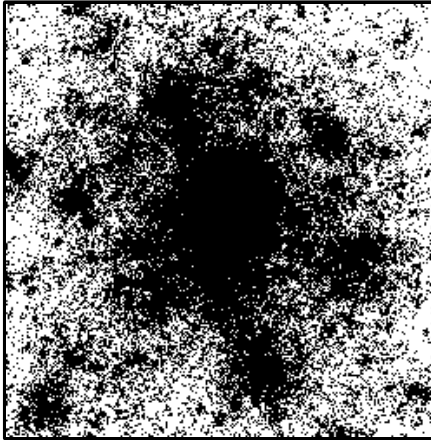
- small exponent fills faster
- large exponent more compact

Percolation transition

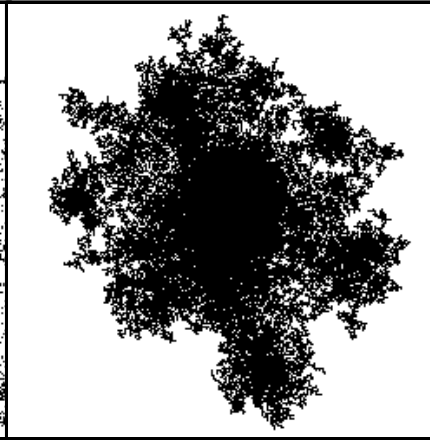
maximum in the
number of clusters



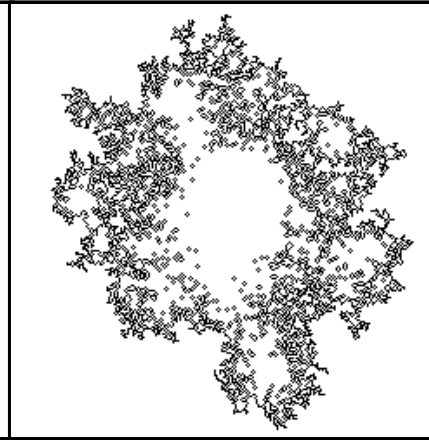
Boundary



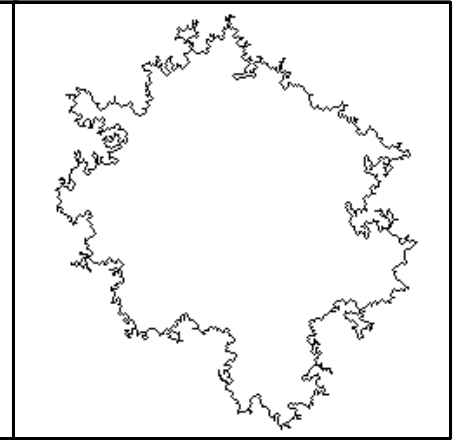
1 configuration



largest
component

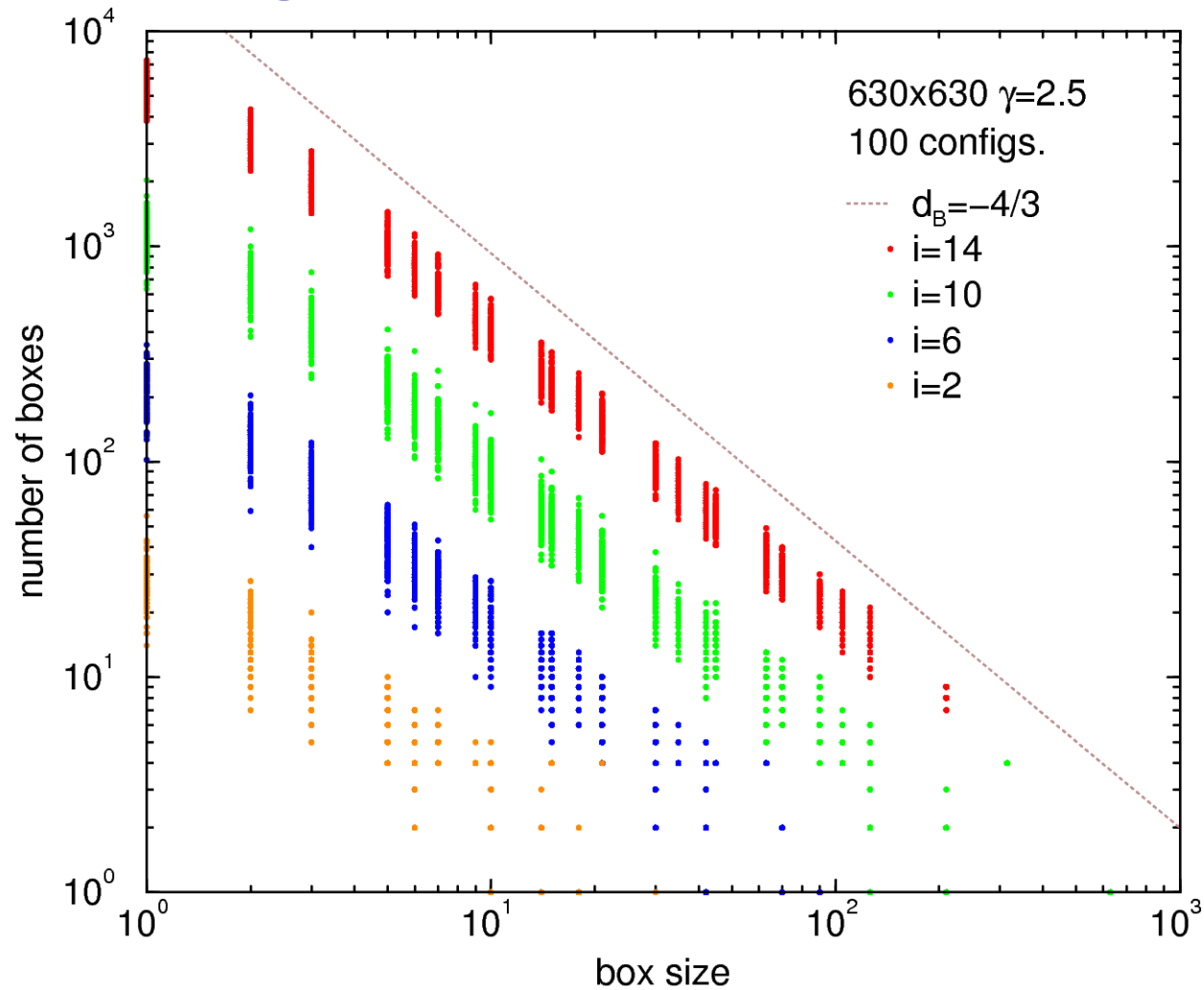


boundary

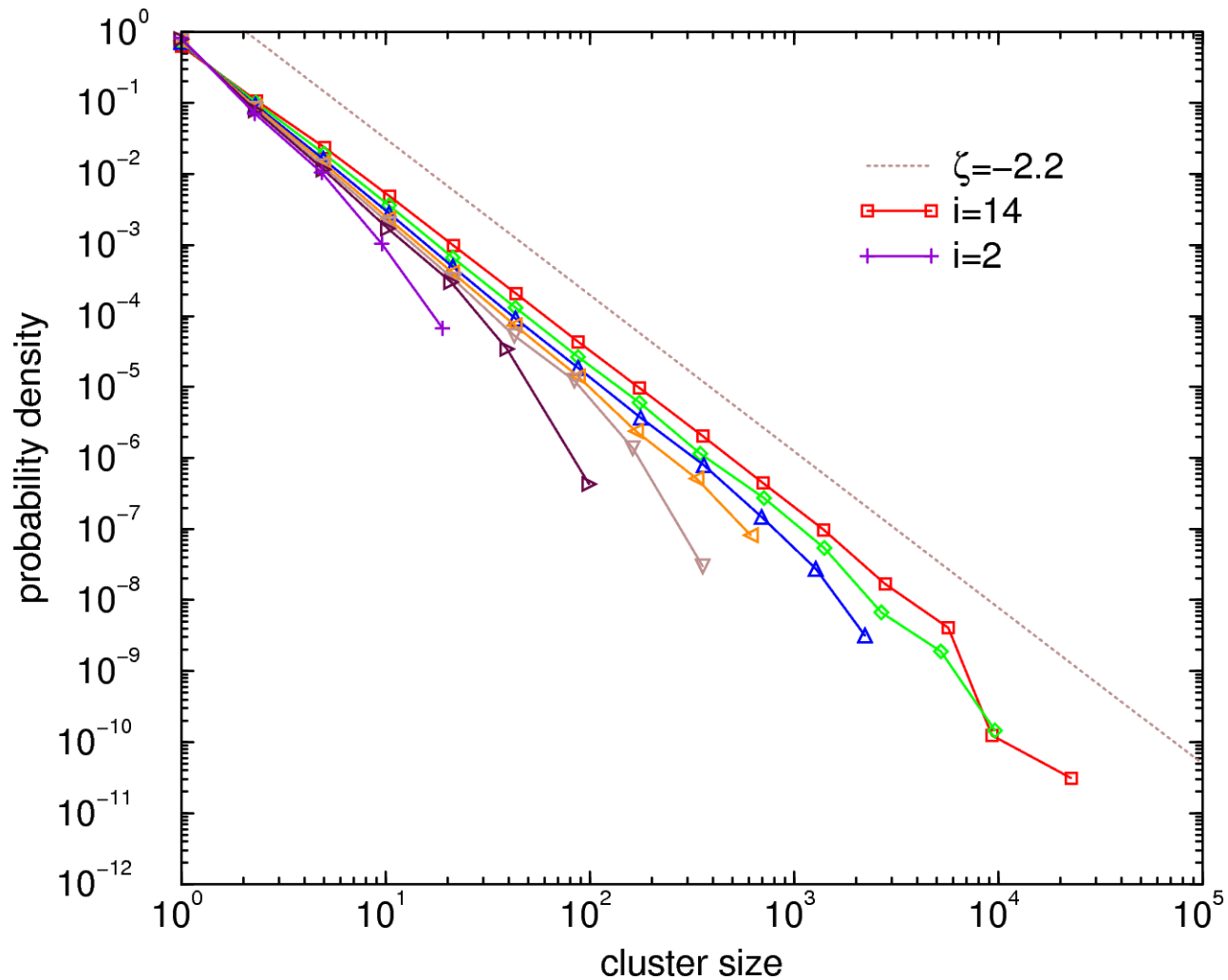


disregarding
inclusions

Fractal dimension of boundary: box covering



Cluster size distribution (without largest)



Summary

Simple & intuitive approach

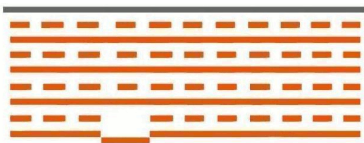
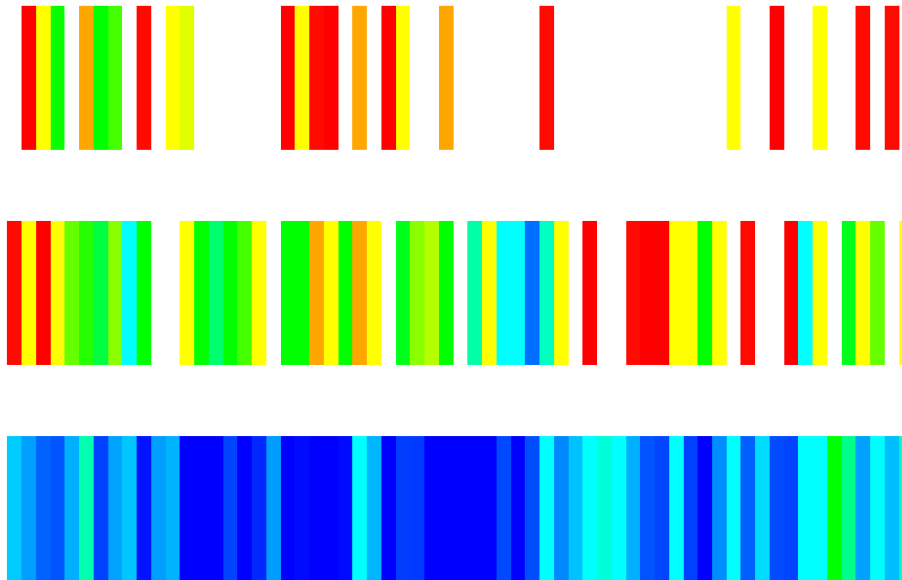
Fractal boundary

Zipf's law

more work necessary

for characterization

Thank you for your attention.



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